

Verifying Generics and Delegates

Kasper Svendsen
Lars Birkedal
Matthew Parkinson

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Introduction

HO separation logic for C# subset with generics and delegates

- Hoare-style program logic for proving functional correctness
- Separation logic for modular reasoning about state

In HOSL & Hoare Type Theory one can reason about

- polymorphism using universal quantification over predicates
- first-class functions using nested Hoare triples

We extend these techniques to reason about C#

- Main challenge: C# variable capture

C# variable capture

Example

```
public delegate Y Func<Y> ();
```

```
Func<int> counter() {  
    int x = 0;  
    return delegate () { return ++x; };  
}
```

C# semantics

- Inline delegate captures the location of x
- Lifetime of captured x extended to lifetime of delegate

Outline

Introduction

Generics

Delegate clients

Capturing delegates

Setup

C# subset

- Basic imperative features + generics + delegates

Assertion logic

- Logic for reasoning about computational states
- Higher-order separation logic
- Spatial connectives, emp , $*$, $\neg*$, for controlling aliasing
- State assertions, $M.f \mapsto N, \dots$, for describing state

Specification logic

- Logic for relating initial and terminal state

Example – Integer list

```
class Node {  
    Node next;  
    Integer val;  
}
```

Example – Integer list

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class Node {
  Node next;
  Integer val;
}
```

- Representation predicate

$$list(x, \varepsilon) \stackrel{def}{=} x = null$$

$$list(x, a \cdot \alpha) \stackrel{def}{=} \exists n, \exists v. x.next \mapsto n * x.val \mapsto v * \underline{Int(v, a)} * list(n, \alpha)$$

- $Int(v, a)$: v is a representation of the integer a

Example – Generic list

```

class Node<X> {
  Node<X> next;
  X val;
}

```

- Representation predicate

$$list(x, \varepsilon, P) \stackrel{def}{=} x = null$$

$$list(x, a \cdot \alpha, P) \stackrel{def}{=} \exists n, \exists v. x.next \mapsto n * x.val \mapsto v * \underline{P(v, a)} * list(n, \alpha, P)$$

- $P(v, a)$: v is a representation of a

Example – Fold

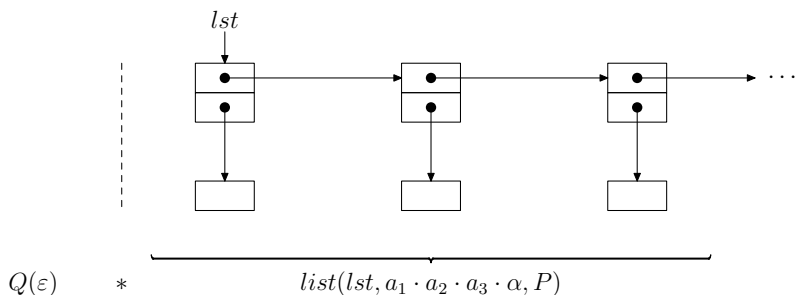
```
void fold<X>(Node<X> lst, Action<Node<X>> f) {  
    if(lst != null) {  
        Node<X> next = lst.next;  
        f(lst);  
        fold(next, f);  
    }  
}
```

Example – Fold

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void fold<X>(Node<X> lst, Action<Node<X>> f) {  
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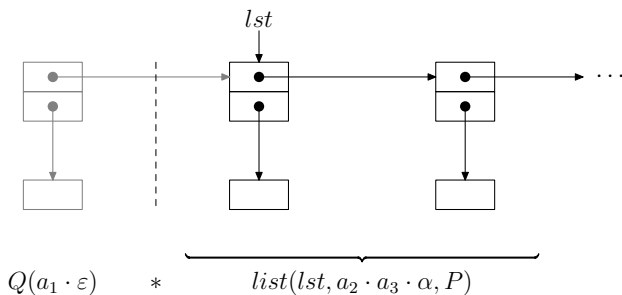
- foreach
- Stateful fold-right – accumulator maintained by delegate

Example – Fold



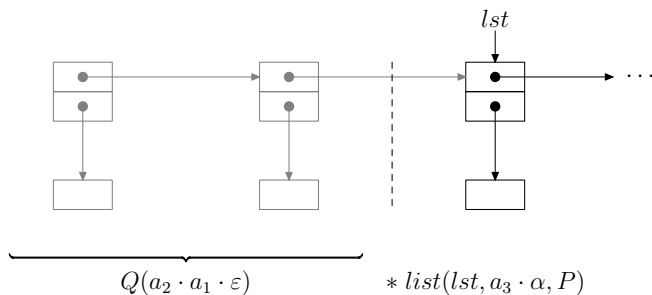
- $Q(\alpha)$: accumulator predicate; state after having folded over α

Example – Fold



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Example – Fold

Specification

void fold⟨X⟩(Node⟨X⟩ lst, Action⟨Node⟨X⟩⟩ f) { ... }

$\forall \alpha : \mathbf{Val}. \forall P : \mathbf{Val} \times \mathbf{Val} \rightarrow \mathbf{Prop}. \forall Q : \mathbf{Val} \rightarrow \mathbf{Prop}.$

$\{ list(lst, \alpha, P) * Q(\varepsilon) * \forall a, \beta, y : \mathbf{Val}.$

$f \mapsto \langle (x). \{ x.next \mapsto _ * x.val \mapsto y * P(y, a) * Q(\beta) \}$
 $\{ Q(a \cdot \beta) \} \rangle \}$

$\{ Q(rev(\alpha)) \}$

- $Q(\alpha)$: accumulator predicate; state after having folded over α
- $rev(\alpha)$: mathematical reverse function
- $M \mapsto \langle (\phi). \{ P \}_- \{ Q \} \rangle$: M denotes delegate satisfying spec

Example – Fold

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Variable capture

Increment example

```
int x = 0;
```

```
Action f = delegate () {
```

```
    x++;
```

```
};
```

```
f();
```


Variable capture

Increment example

```
int x = 0;
```

```
Action f = delegate () {
```

```
    { x = n }
```

```
    x++;
```

```
    { x = n + 1 }
```

```
};
```

```
{ x = 0 *  $\forall n. f \mapsto \langle \{ x = n \} - \{ x = n + 1 \} \rangle$  }
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Variable capture

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```

```
f();  $\Rightarrow f \mapsto \langle \{ 0 = 0 \} - \{ 0 = 1 \} \rangle$ 
```

Variable capture

Increment example

```
int x = 0;
Action f = delegate () {
    { emp }
    x++;
    { emp }
};
{ x = 0 * f  $\mapsto$   $\langle$ { emp }-{ emp } $\rangle$  }
f();
```

Variable capture

Increment example

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int x = 0;
Action f = delegate () {
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f();
```

Issues

- How to refer to captured variables in nested specs
- How to keep track of potentially modified variables

Variable capture

Variable assertions

- Extend assertion logic with variable assertions $M \overset{s}{\mapsto} N, \&x$
 - $M \overset{s}{\mapsto} N$: location M is allocated on the stack and contains N
 - $\&x$: denotes location of program variable x

Variable capture

Variable assertions

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Inline delegate

```
int x = 0;
```

```
Action f = delegate () {
```

```
    { P }
```

```
    B
```

```
    { Q }
```

```
};
```

```
{ x = 0 * f  $\mapsto$   $\langle$  {  $\exists y. \&x \xrightarrow{s} y * [y/x]P$  } - {  $\exists y. \&x \xrightarrow{s} y * [y/x]Q$  }  $\rangle$  }
```

Variable capture

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```
};
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{ x = 0 *  $\forall n. f \mapsto \langle \{ \&x \overset{s}{\mapsto} n \} - \{ \&x \overset{s}{\mapsto} n + 1 \} \rangle$  }
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Variable capture

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Variable capture

Aliasing

- Var. assertions introduce aliasing in reasoning about variables:
- Build separation into specification logic:
 - Can either reason directly or indirectly, but not both
 - Reason directly about variables in the program var. ctx. ϕ

Variable capture

Aliasing

- Var. assertions introduce aliasing in reasoning about variables:
- Build separation into specification logic:
 - Can either reason directly or indirectly, but not both
 - Reason directly about variables in the program var. ctx. ϕ
 - Hoare's assignment rule thus stil sound

$$\frac{\phi; \psi \vdash P : \mathbf{Prop} \quad x, y \in \phi}{\phi; \psi \vdash \{P[y/x]\}x := y\{P\}}$$

Variable capture

Capturing delegates

- Verify body using Hoare treatment of variables
- Switch to SL treatment of captured variables in nested spec
- Switch back to Hoare treatment of variables to verify calls

Variable capture

Capturing delegates

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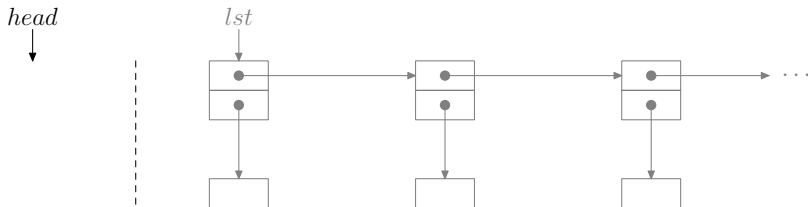
$$\frac{x \notin FV(s) \quad \phi; \psi \vdash \{\exists x : \mathbf{Val}. I \mapsto^s x * P\}s\{\exists x : \mathbf{Val}. I \mapsto^s x * Q\}}{\phi, x; \psi \vdash \{\&x = I \wedge P\}s\{Q\}}$$

Example – In-place reverse

```
Node<X> reverse<X>(Node<X> lst) {  
    Node<X> head = null;  
    fold<X>(lst, delegate (Node<X> x) { x.next = head; head = x; });  
    return head;  
}
```

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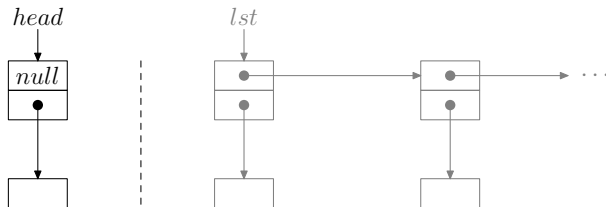


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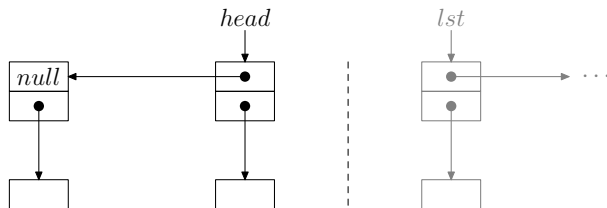


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```

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$$\{ \text{list}(lst, \alpha, P) \}$$

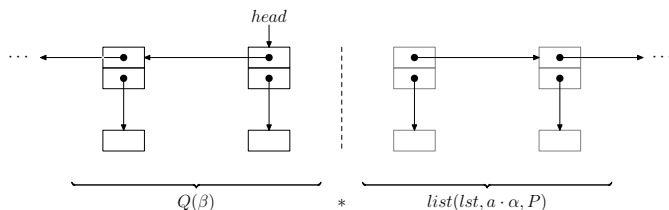
$$\{ r.\text{list}(r, \text{rev}(\alpha), P) \}$$

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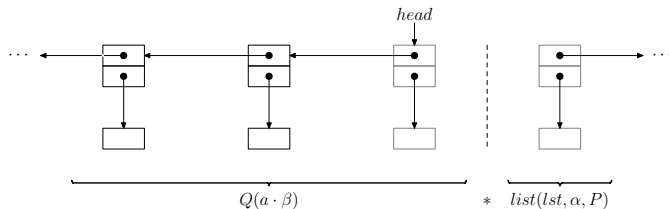
where $Q(\alpha) = \exists n : \mathbf{Val.} \ \&head \mapsto n * list(n, \alpha, P)$

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where $Q(\alpha) = \exists n : \mathbf{Val.} \ \&head \mapsto^s n * \text{list}(n, \alpha, P)$

Conclusion

Generics and non-capturing delegates

- HOL & nested Hoare triples (standard)

Capturing delegates

- Separation logic treatment of variables
- Variable separation build into specification logic
- Unified treatment of local state on the heap and/or stack
- Reasoning standard when there is no capturing